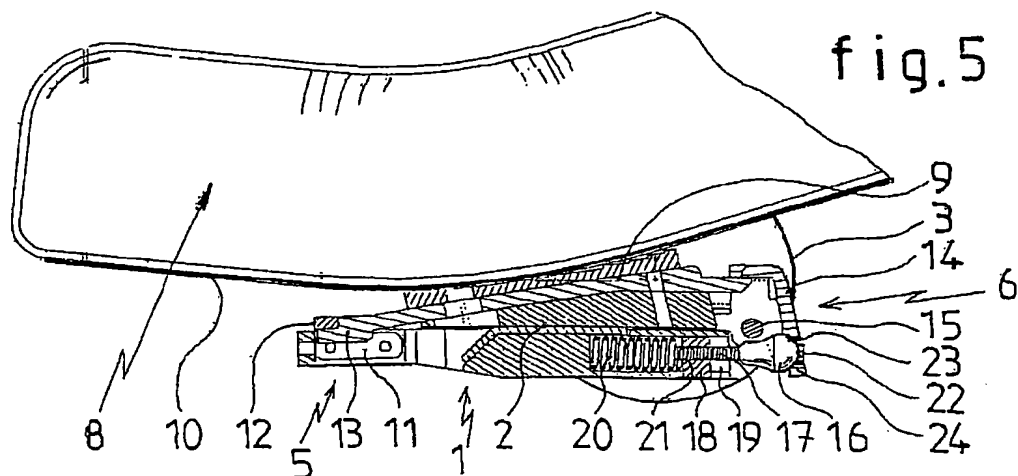
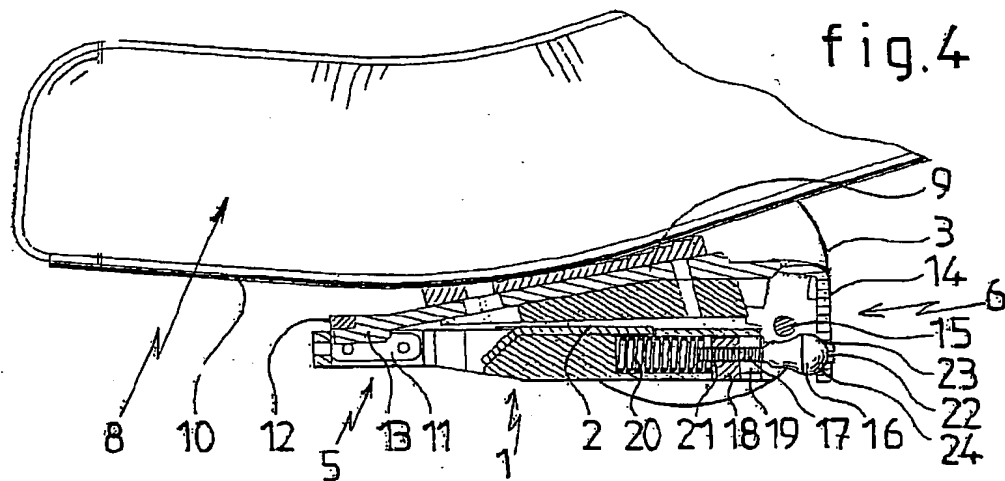
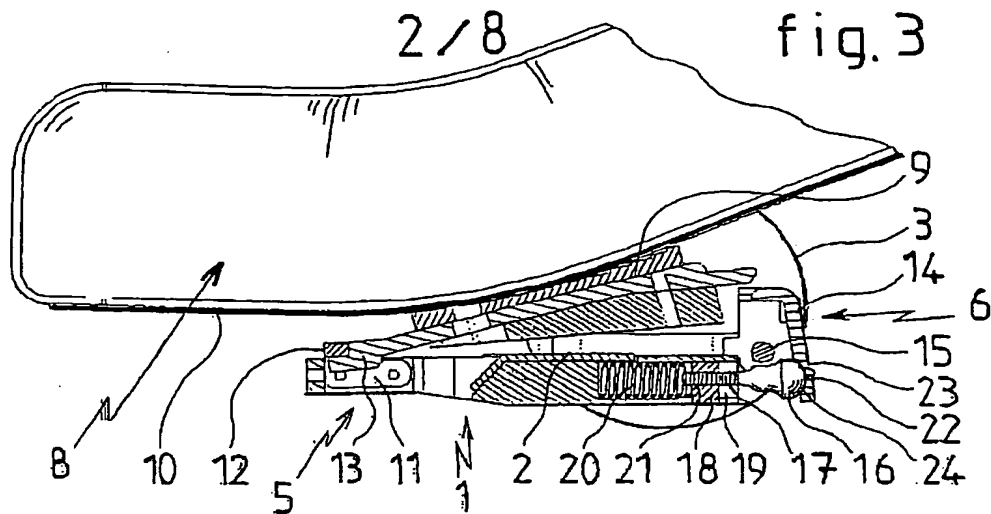


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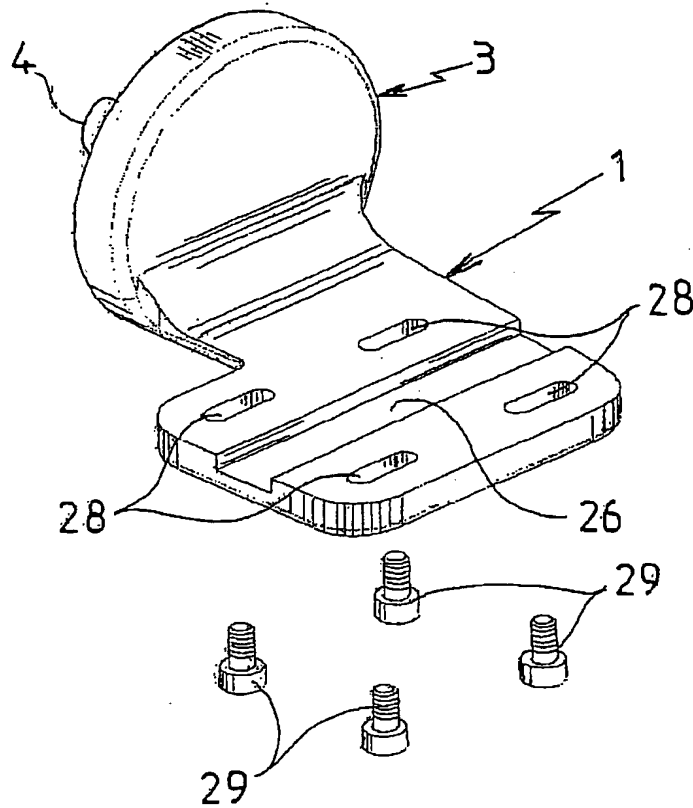
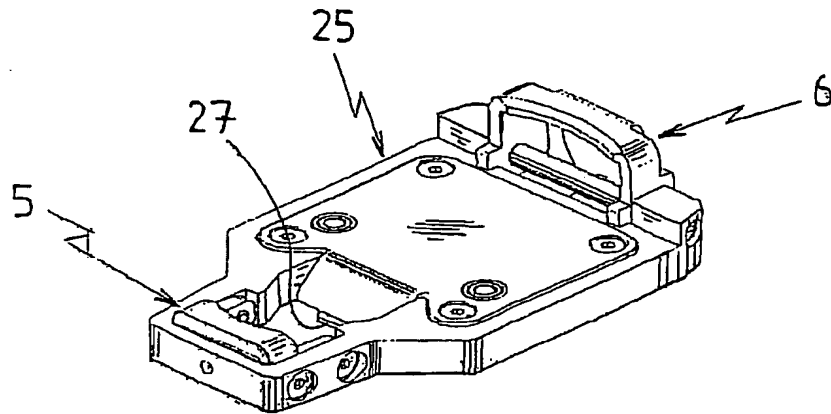
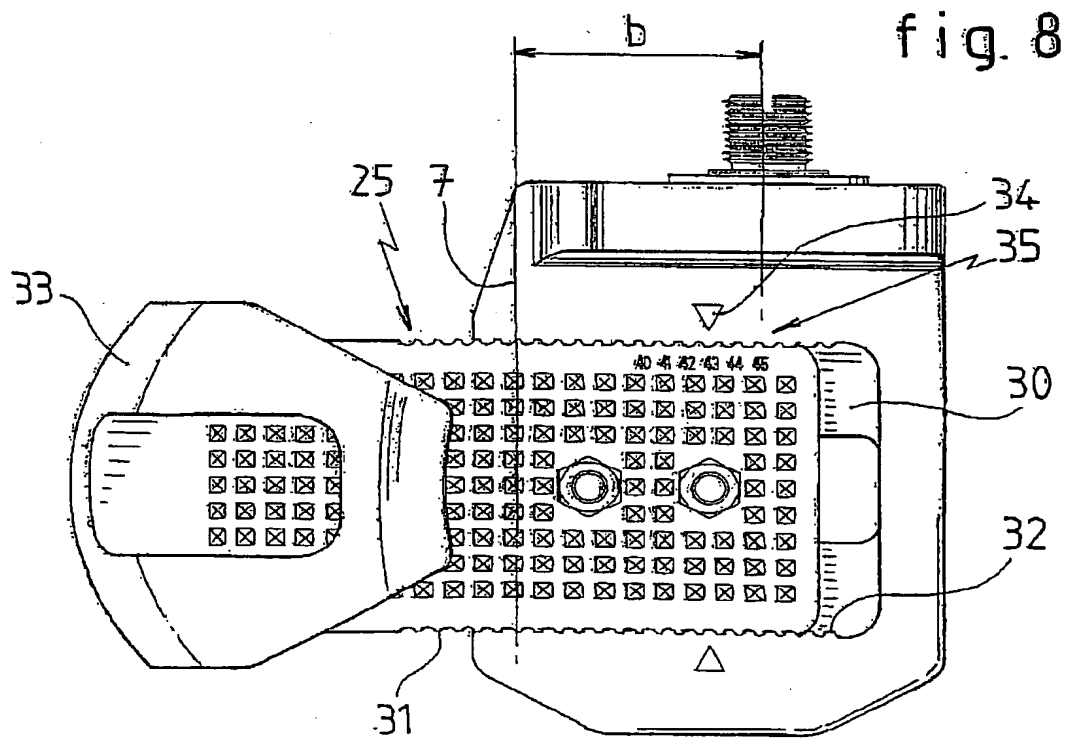
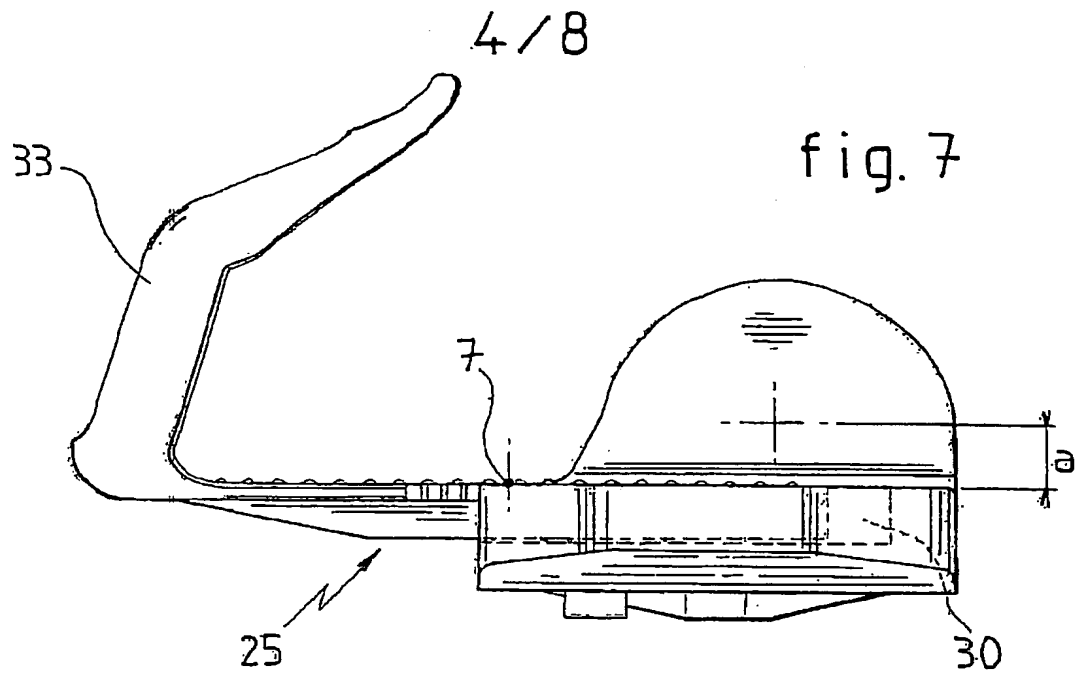
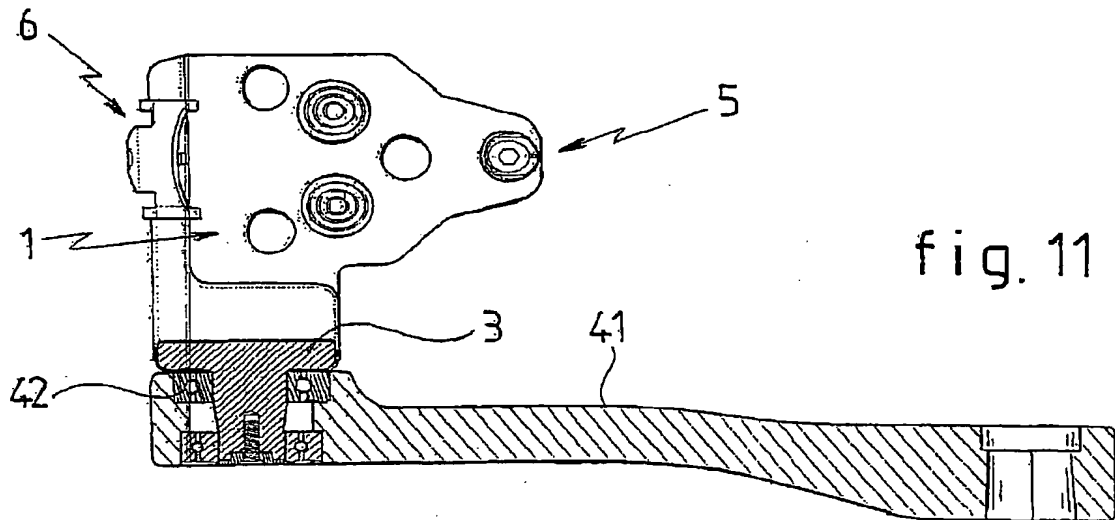
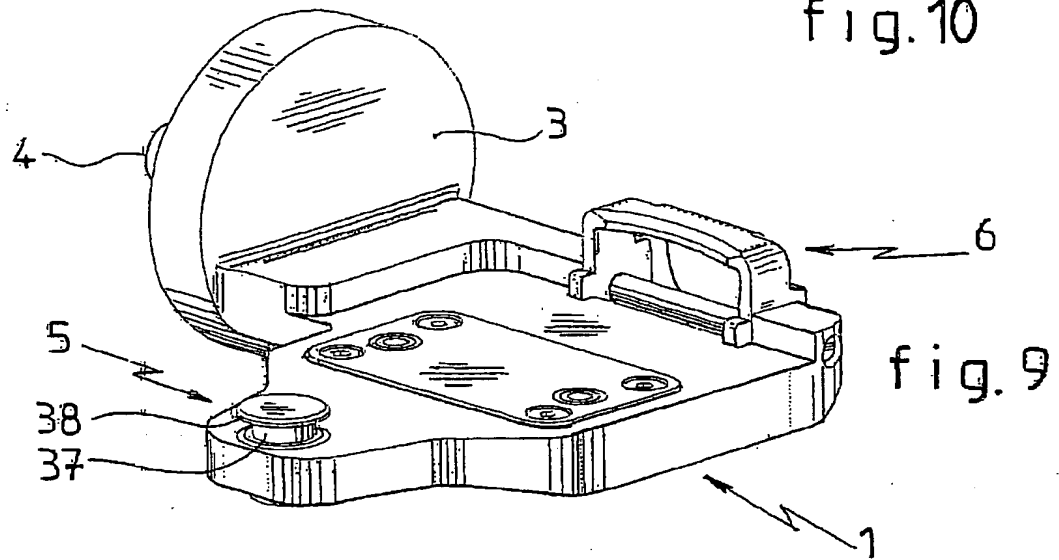
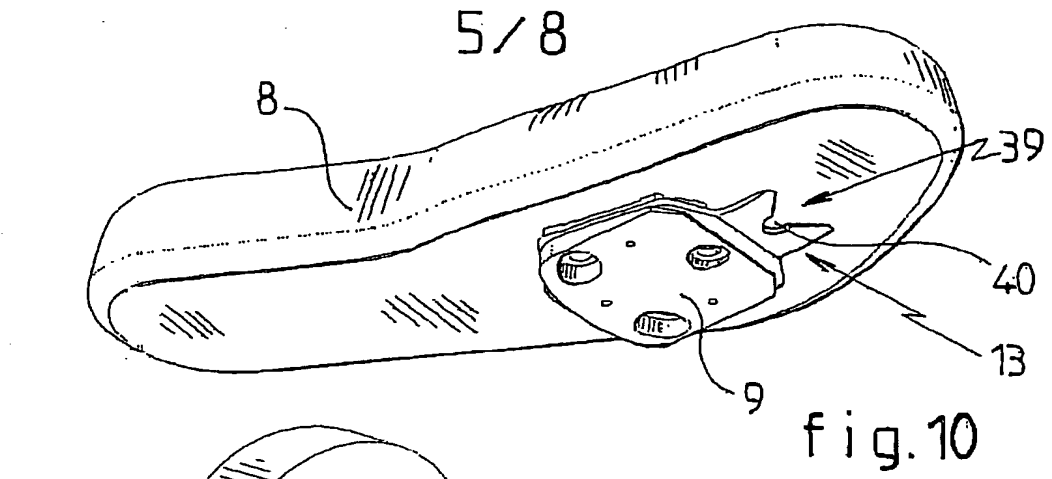


fig. 6







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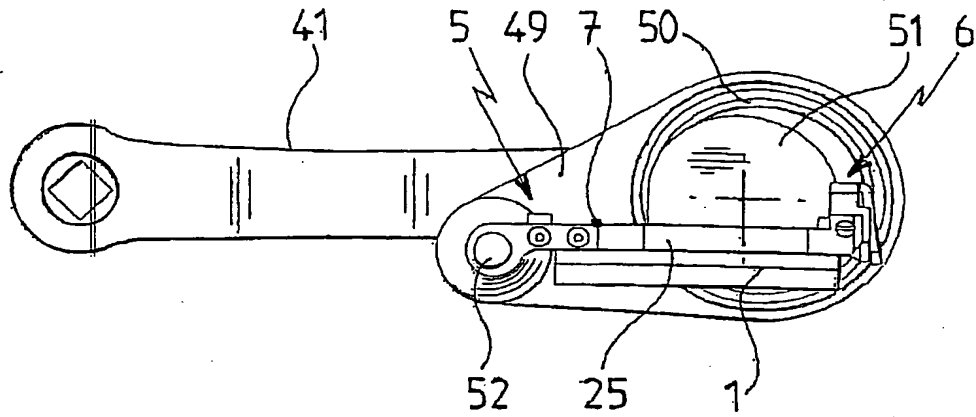


fig. 14

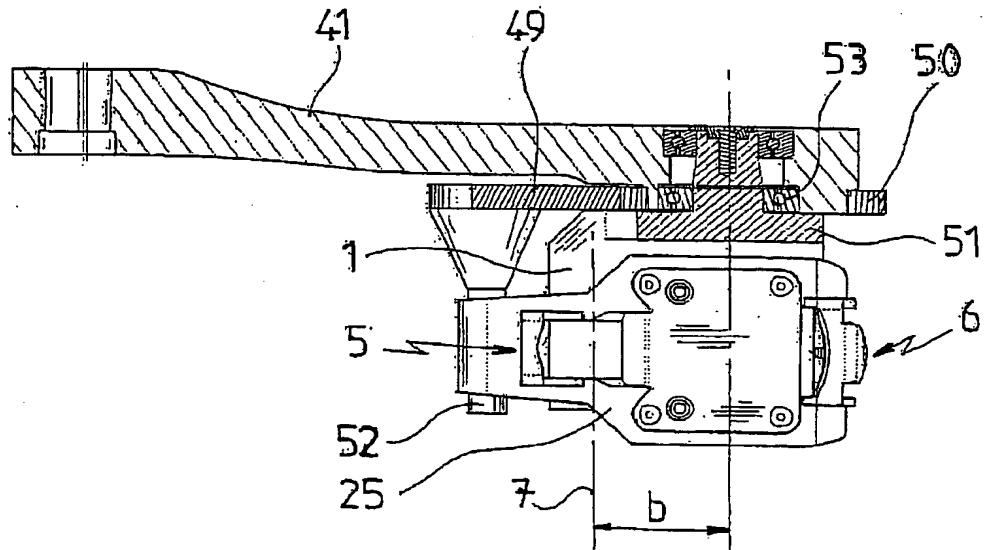


fig. 15

Figure 9 is a schematic diagram of a four-bar linkage mechanism. The mechanism consists of four links (1, 2, 3, 4) connected by revolute joints. Link 1 is the fixed frame, and link 2 is the crank. Link 3 is the coupler, and link 4 is the rocker. The diagram shows the mechanism in a specific configuration, with dimensions b and g indicated. The labels 5, 6, 7, 25, 50, 51, and 52 point to various components and joints.

fig. 16